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CENTRO NAZIONALE PER LA MOBILITÀ SOSTENIBILE

XXXIX Riunione Annuale dei Ricercatori di Elettrotecnica

# Experimental Evaluation of Wireless Charging Systems: the DEXTER Project



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University of Cassino and Southern Lazio





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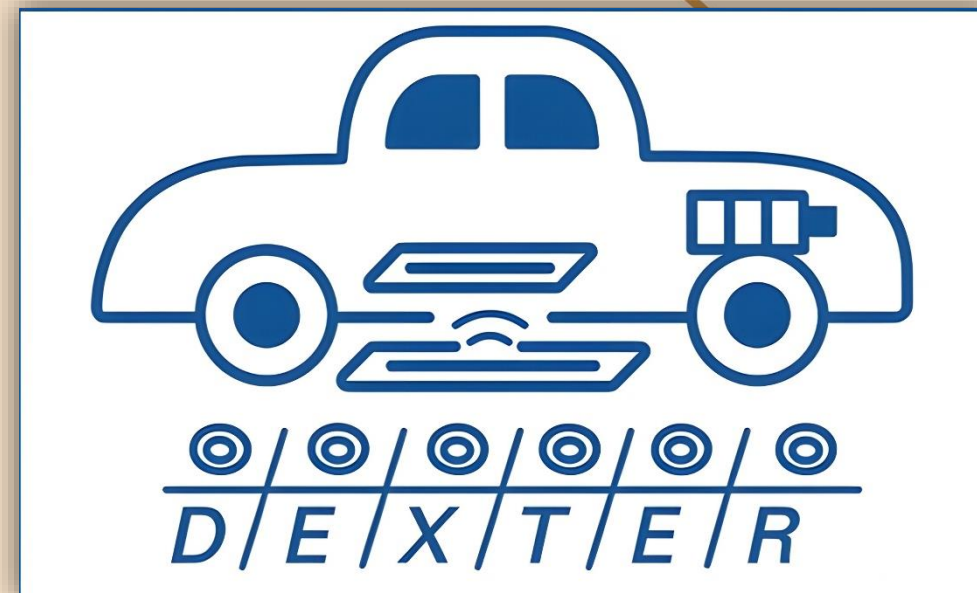
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## ***Progetto DEXTER***

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NextGenerationEU – Piano Nazionale  
Resistenza e Resilienza (PNRR) – Missione 4  
Componente 2 Investimento 1.4 –  
Progetto CN\_00000023 denominato  
Sustainable Mobility Center (MOST)



Development of an **E**nhanced  
**eX**perimental pro**T**otype of  
wir**E**less charge**R**

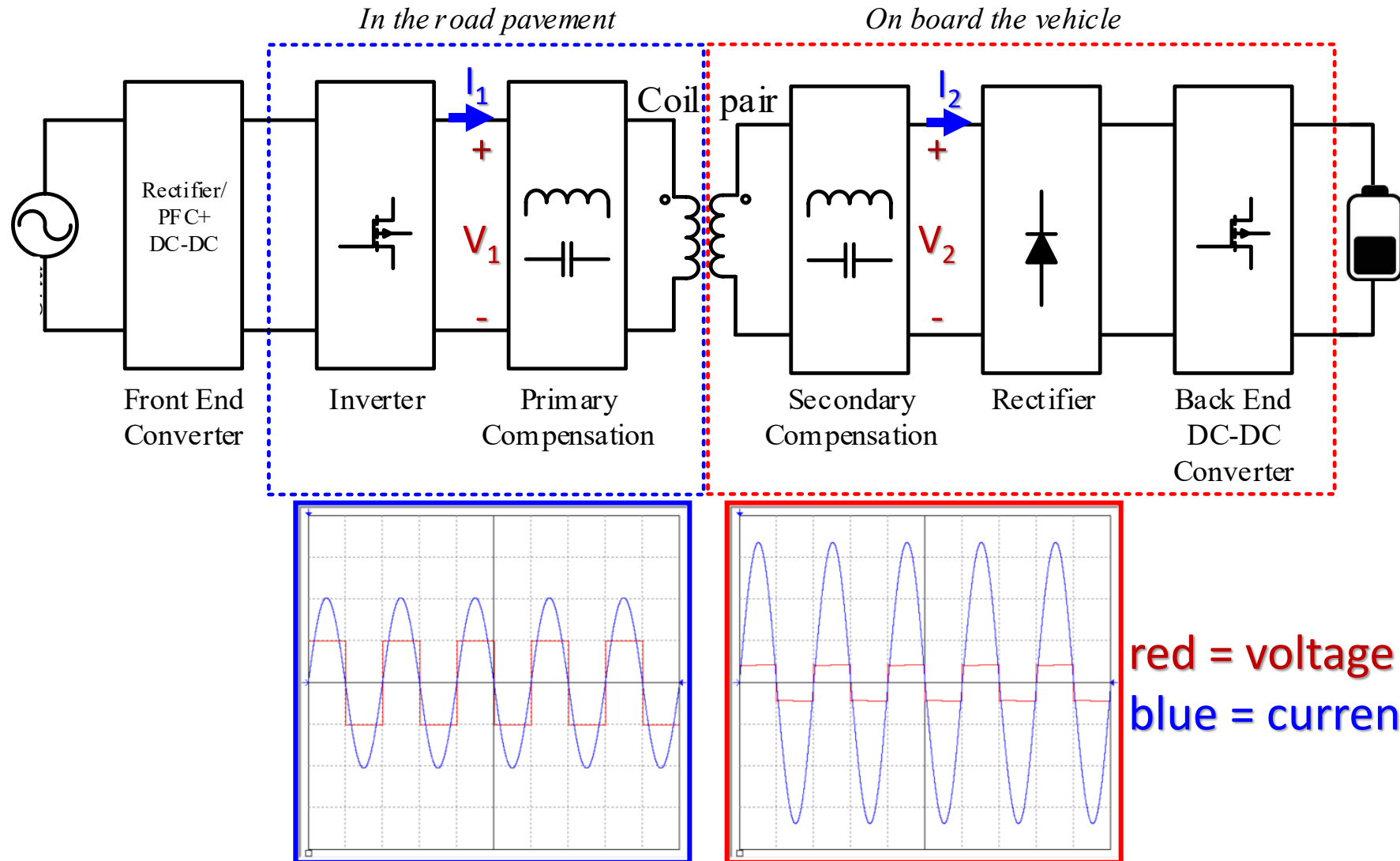


Missione 4 Istruzione e Ricerca

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# Wireless Power Transfer Systems: powertrain architecture





## Wireless Power Transfer Systems Challenges

- Coils design and performance characterization (*mutual inductance*)
- Compensation topologies (*series/parallel/hybrid*)
- Power electronics design and system's performance management (*power/efficiency trade-off, energy/charge transfer rating*)
- EM field analysis and limitations (*coils geometries, ferrites-based shielding, weight trade-off*)
- EM shields design and arrangement (*resonant coils' arrays*)
- Battery Architecture and Management (*charge/discharge patterns, SoC, SoH*)
- Behavioral Modeling (*design-oriented/performance-oriented modeling*)



## DEXTER Project

**GOAL:** Developing a Dynamic Wireless Power Transfer (DWPT) prototyping platform for Electric Vehicle Dynamic Battery Chargers (EV-DBC).

**SYSTEM ARCHITECTURE:** The platform integrates a **3D movement system** of the coils, two digitally-controlled **power electronics units**, a **battery emulator**, a set of **shielding coils**, a **field measurement probe**, and a **control panel**.

**FEATURES:** Hardware-in-the-Loop (HiL) design process, integration of simulations and measurements for multi-objective characterization and optimization, testing of different solutions in terms of coil pairs, shielding coils, power electronics control settings, device-level and system-level behavioral modeling.





## DEXTER team

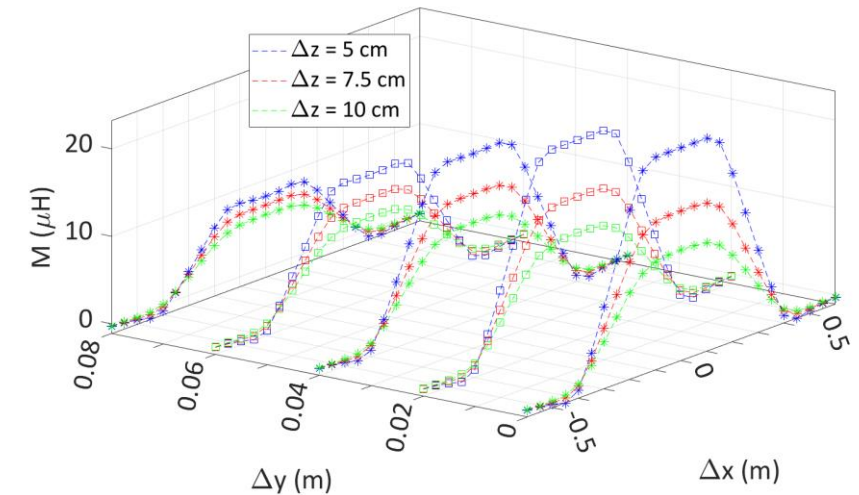
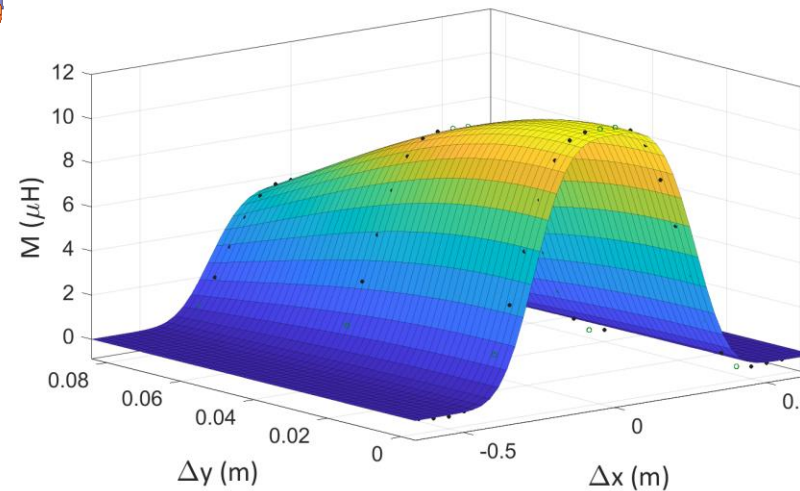
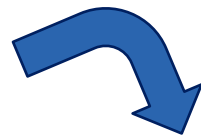
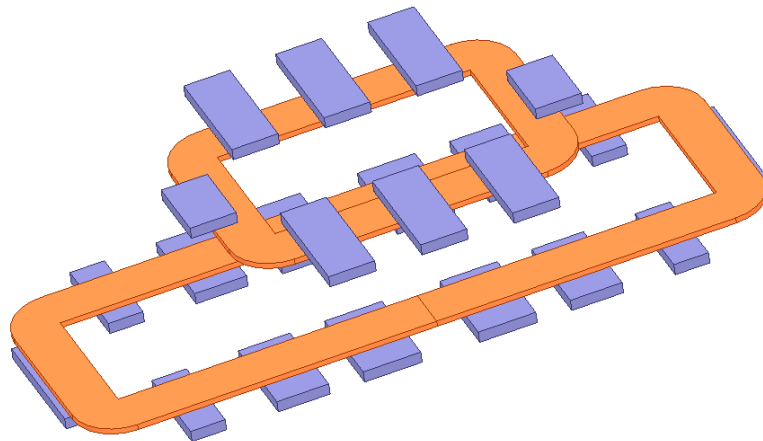
WP.#	WP.NAME		UNICAS	UNUPI	UNISA
1	Prototype and power electronics		contributor	contributor	leader
2	Coils and field modeling		leader	contributor	contributor
3	Electromagnetic Shields Modeling and Design		contributor	leader	contributor
4	Prototype assembly and validation		contributor	contributor	leader

## DEXTER schedule:

**July 1<sup>st</sup>, 2024 – February 28<sup>th</sup>, 2025 (extended to June 30<sup>th</sup> 2025)**



# UNICAS: coils analysis and design



$$M(\Delta x; \Delta y; \Delta z) = a_0 \cdot e^{(a_1 \cdot |\Delta x|^{a_2} + a_3 \cdot |\Delta y|^{a_4})}$$

$$a_i = p_{i0} + p_{i1} \cdot \Delta z + p_{i2} \cdot \Delta z^2$$

coils and ferrites  
optimization

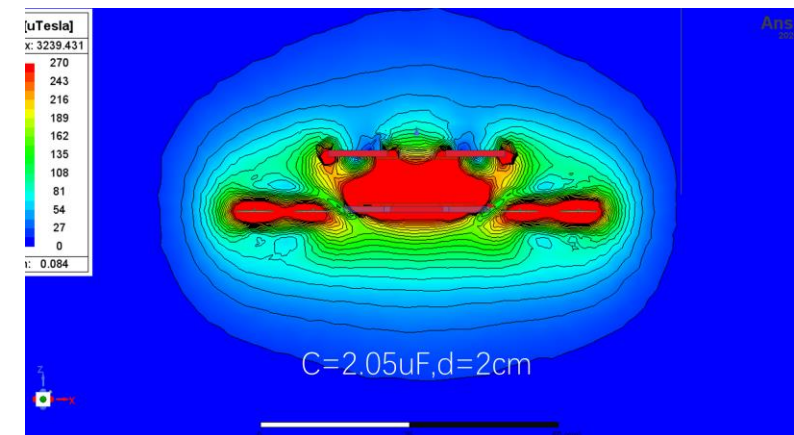
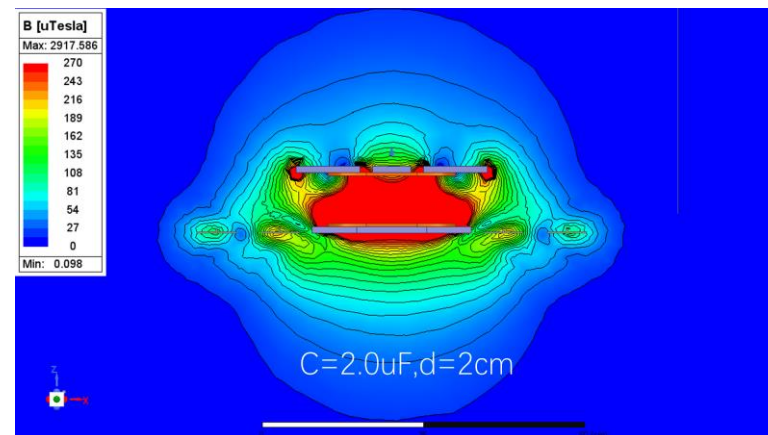
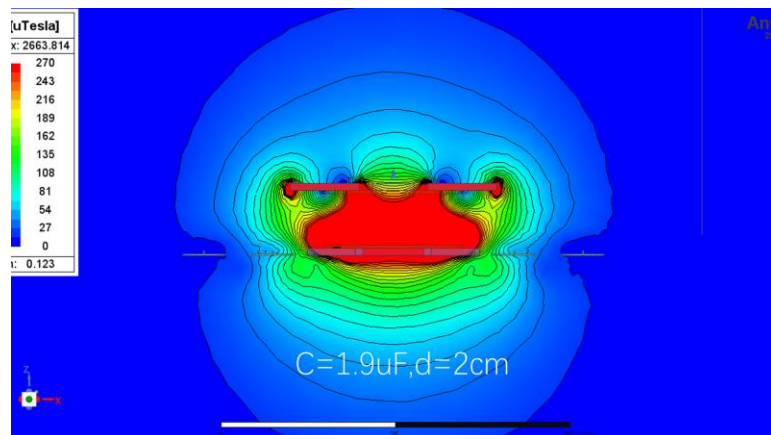
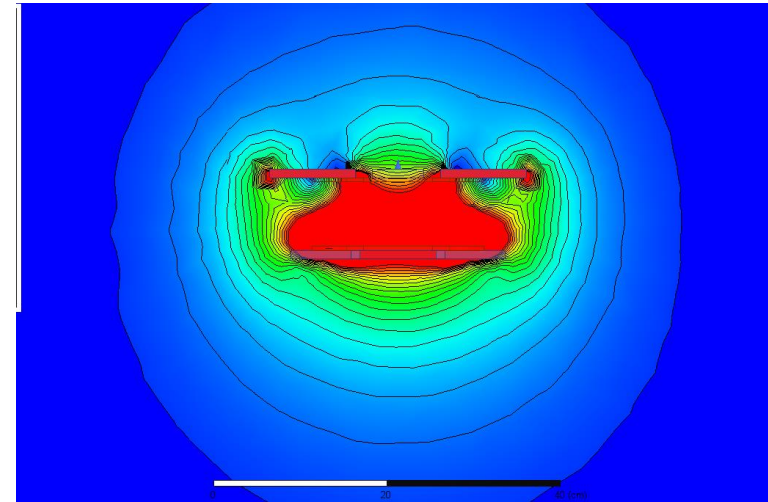
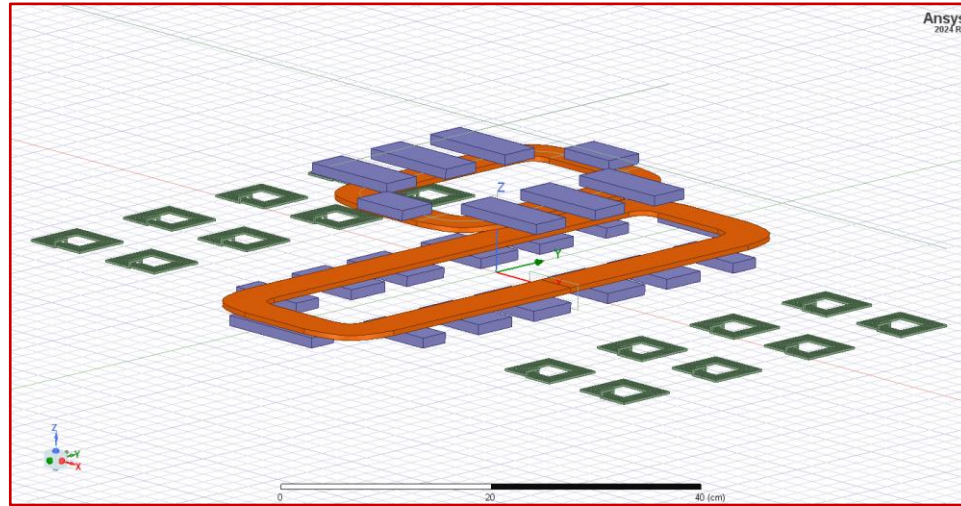
Ansys Maxwell 3D  
simulations

mutual inductance  
modeling

model validation

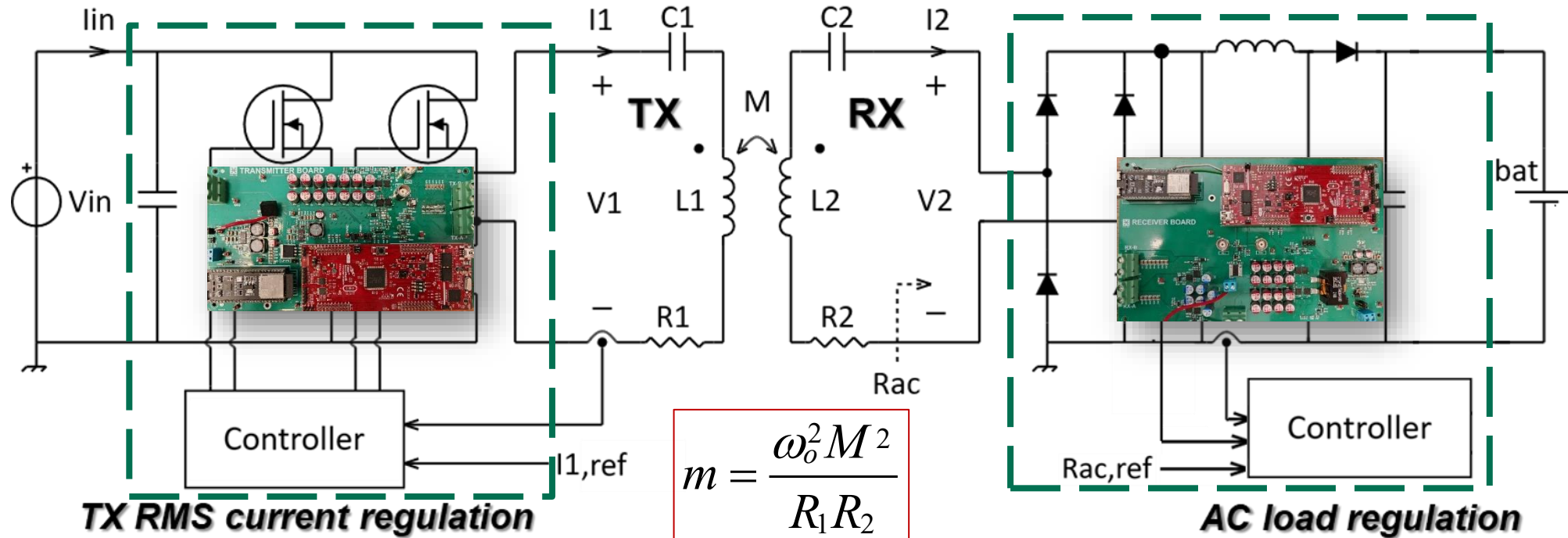


# UNIPi: shielding analysis and design

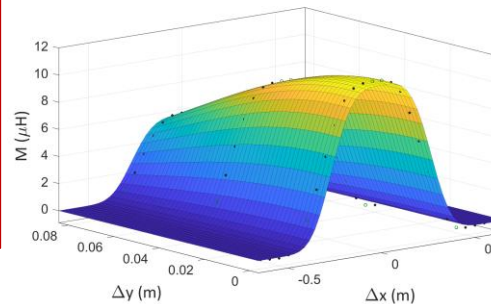




# UNISA: power electronics and system-level analysis and design



$$I_{1,ref} = \frac{4V_{in}}{\pi R_1} \frac{n_{i,max} \left(1 + \sqrt{1 + m_{av}}\right)}{\left(1 + m_{pk} + \sqrt{1 + m_{av}}\right)} = I_{1,opt}$$



$$r_{ac,ref} = \sqrt{1 + m_{av}} = r_{ac,opt}$$



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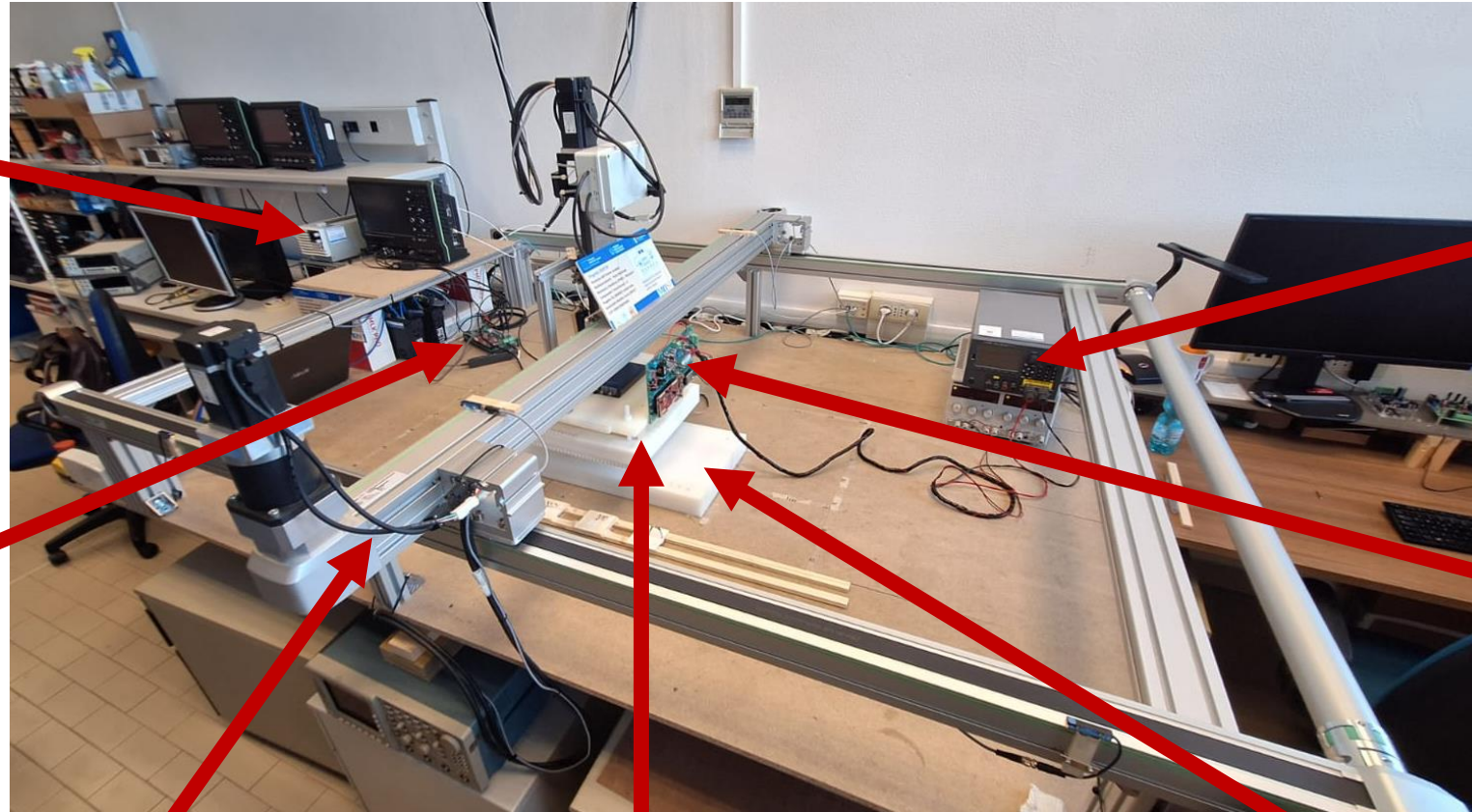
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# DEXTER prototype @ the UNISA Power Electronics Laboratory



DC power  
supply

battery  
emulator

TX power  
electronics

RX power  
electronics

TX coil

RX mover

RX coil





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# DEXTER prototype: power train

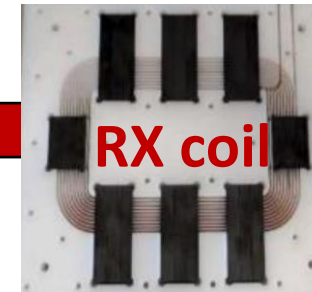
**battery emulator**



**RX power electronics**



**3D RX mover**



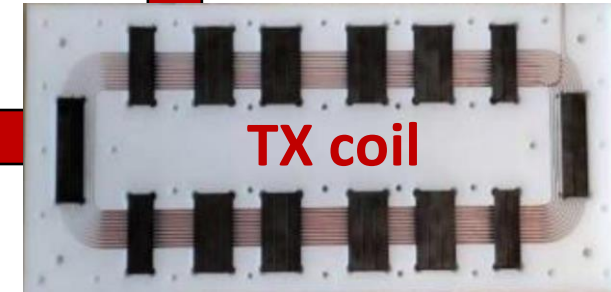
**RX coil**



**DC power supply**



**TX power electronics**



**TX coil**



**shielding  
coils**





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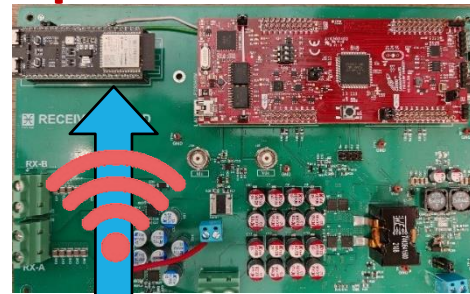
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# DEXTER prototype: control and system management

battery emulator



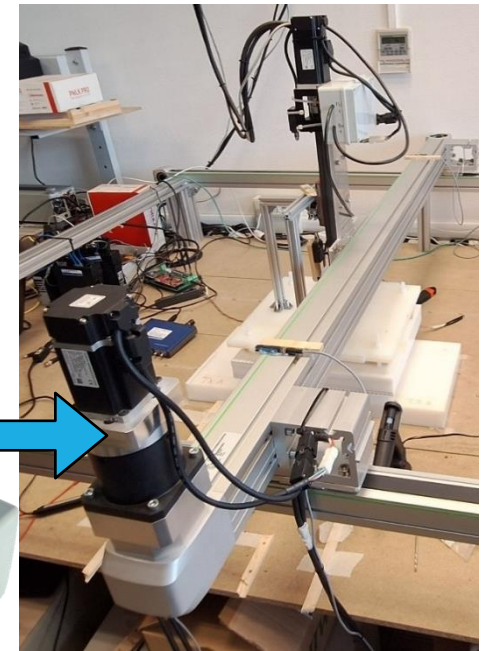
RX power electronics



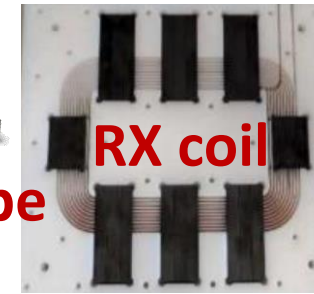
picoscope



3D mover



RX coil



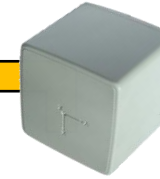
scope



System Control  
and Management

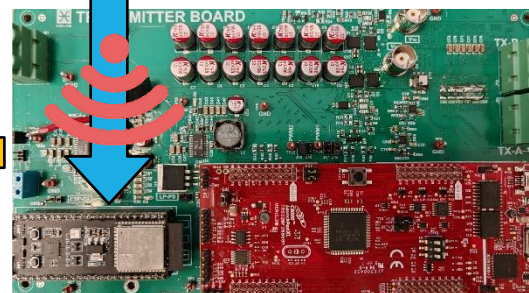


3D field  
probe

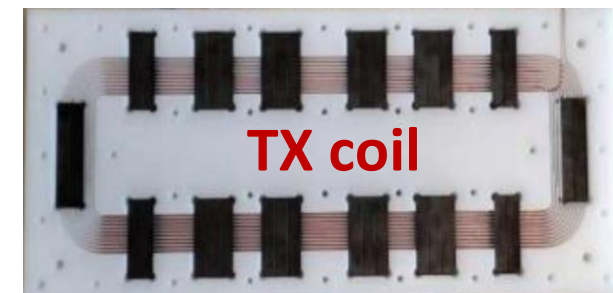


DC power supply

TX power electronics



TX coil



shielding  
coils





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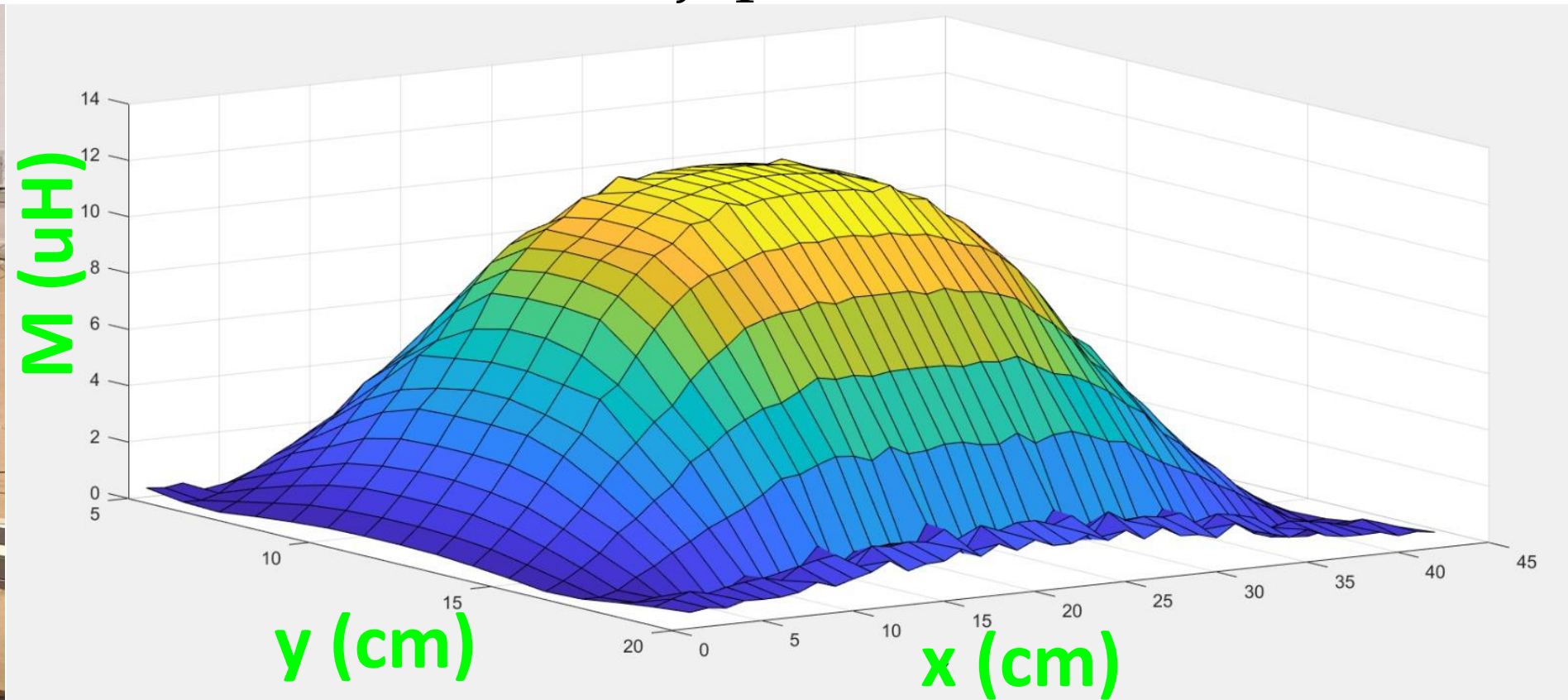
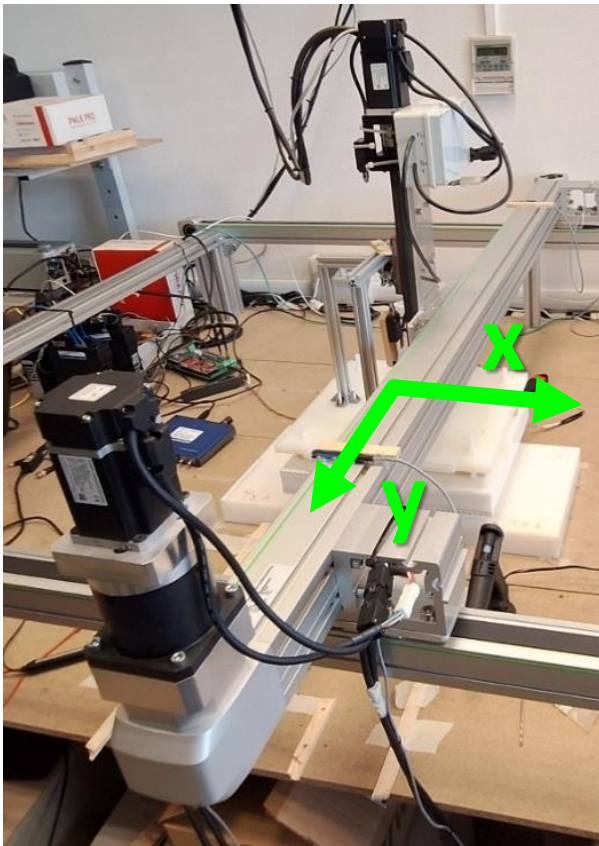
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# DEXTER experiments: automatized mutual inductance mapping

$$M(x, y) = \frac{|\bar{V}_{2,open}(x, y)|}{2\pi f I_1}$$

Experimental results

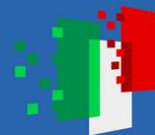




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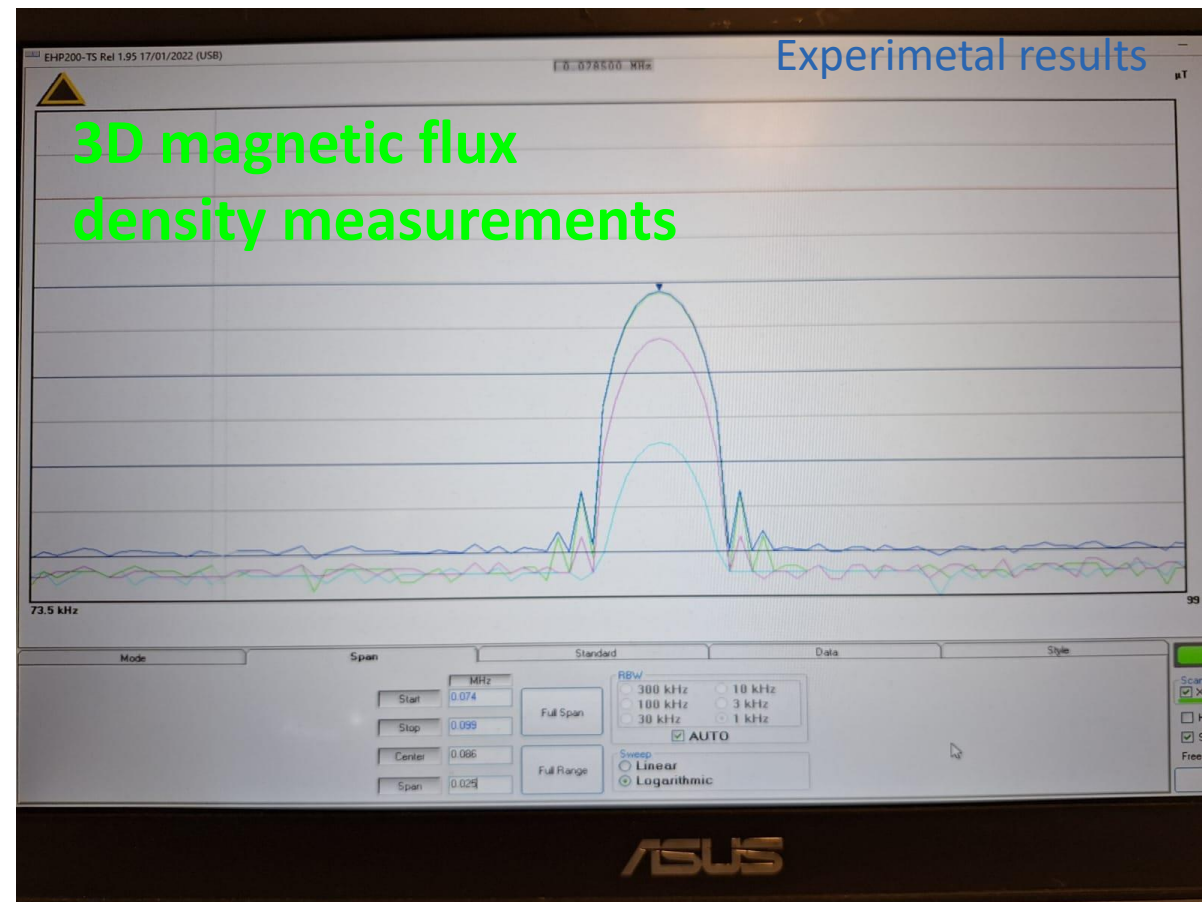
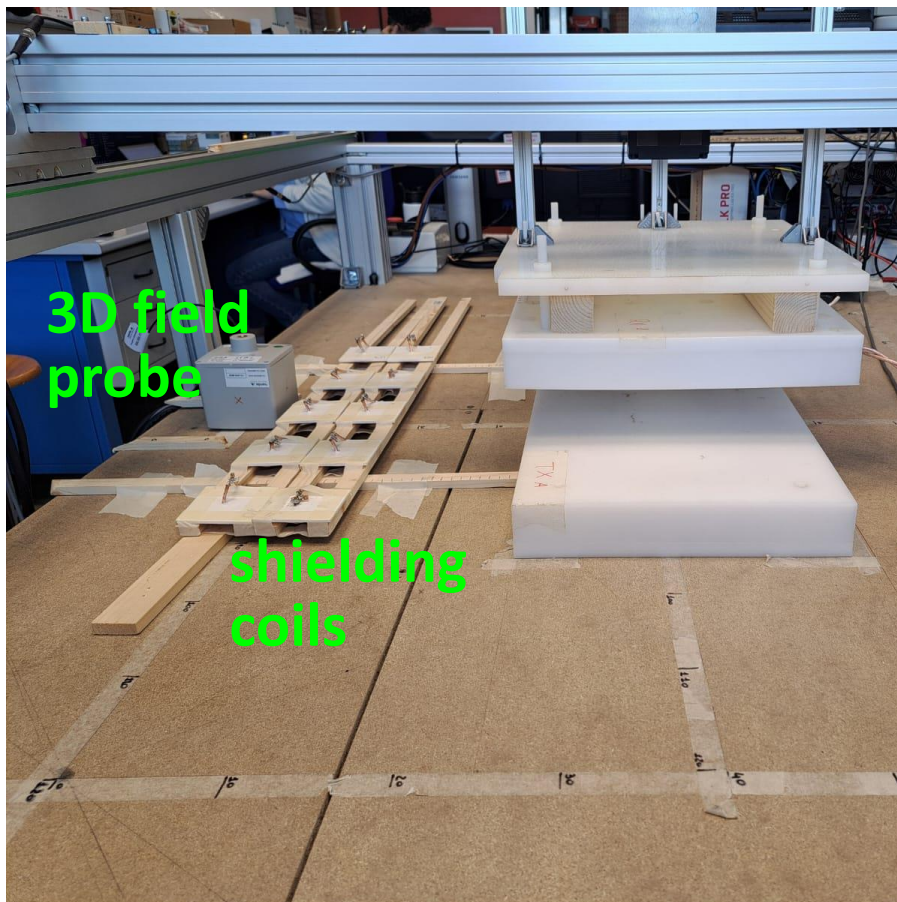
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## DEXTER experiments: field measurements



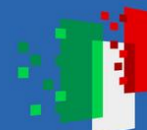




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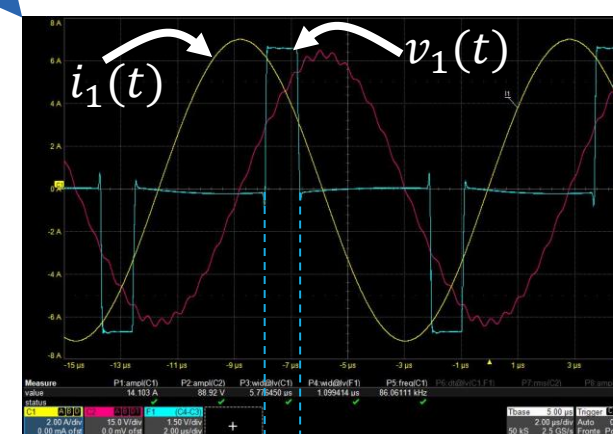
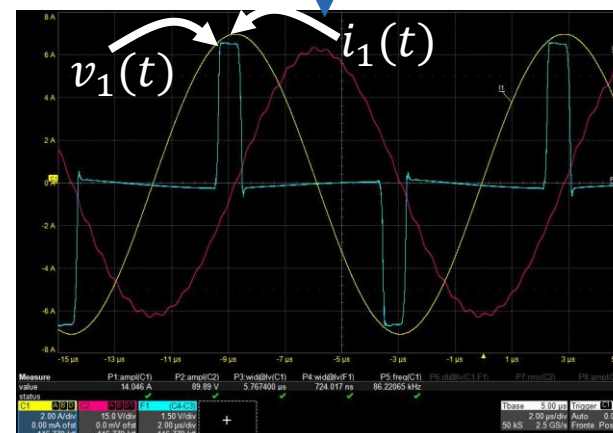
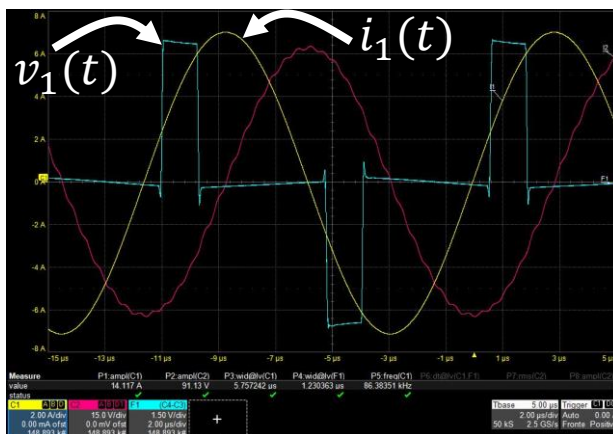
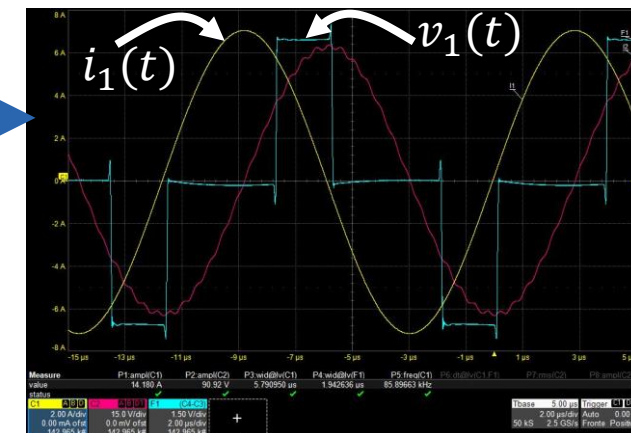
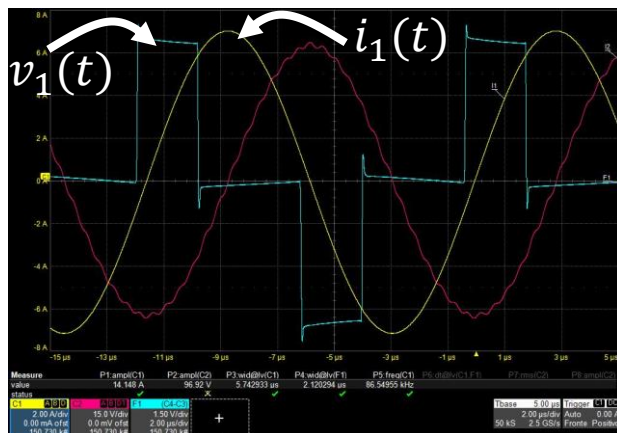
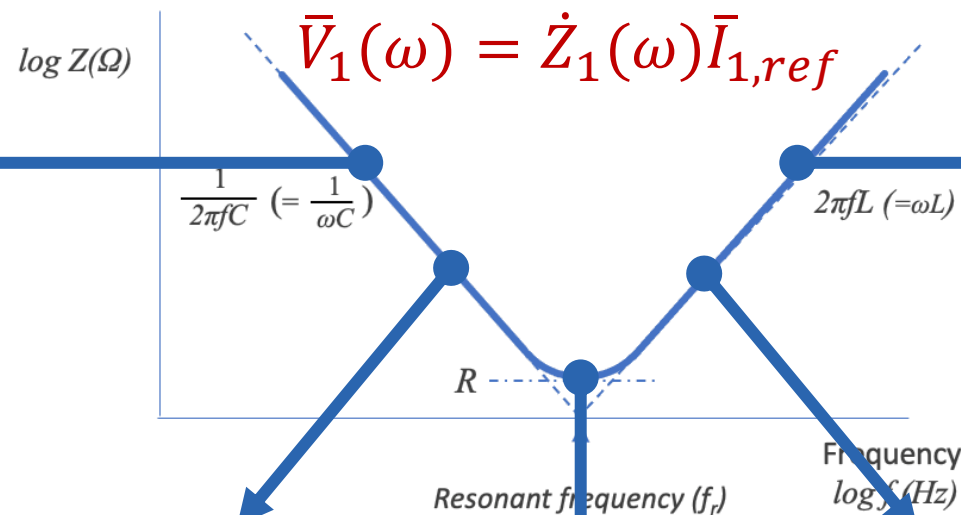
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# DEXTER experiments: automatized resonance frequency detection



$[f_{min}, f_{max}]$   
 $I_{1,ref}$



$$\bar{V}_1(\omega) = \frac{4}{\pi} V_{in} \sin\left(\frac{\omega t_{ON}}{2}\right)$$

$t_{ON}$

**TX power electronics**





# Collaborative research and education opportunities

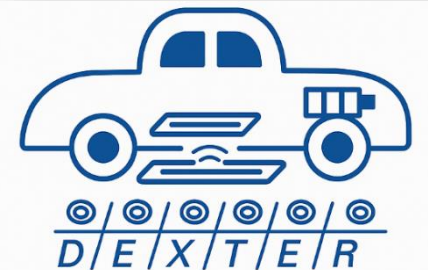
## RESEARCH:

- coils, shielding, power electronics, control modeling and design validation
- battery modeling and validation in static and dynamic WPT charging
- device-level to system-level performance characterization and optimization

## EDUCATION:

- seminars/classes
- training-on-the-job
- master/PhD thesis

**DEXTER deadline:**  
**June 30<sup>th</sup> 2025**



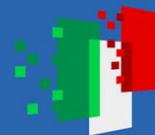




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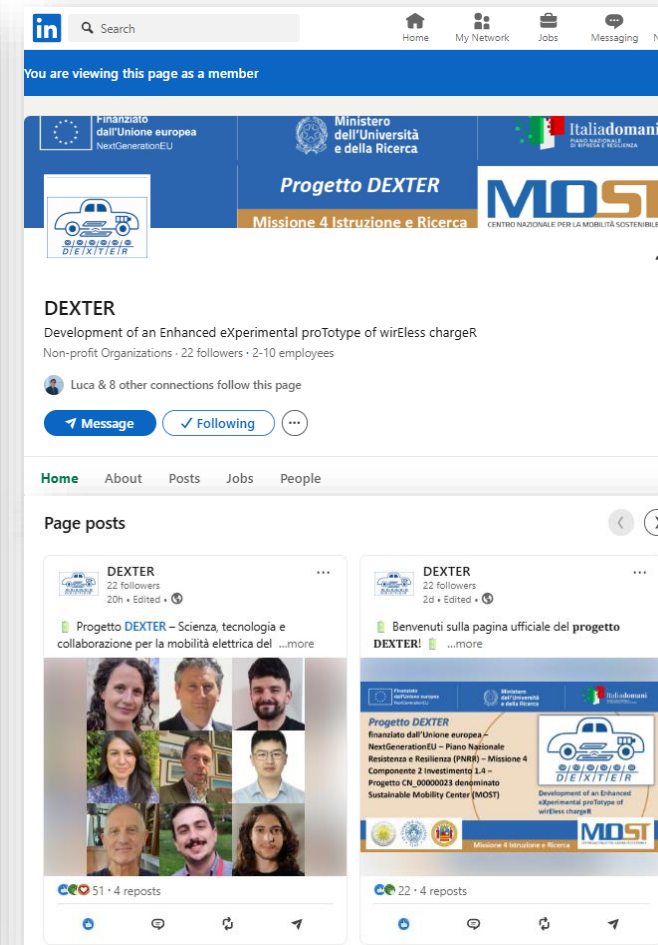
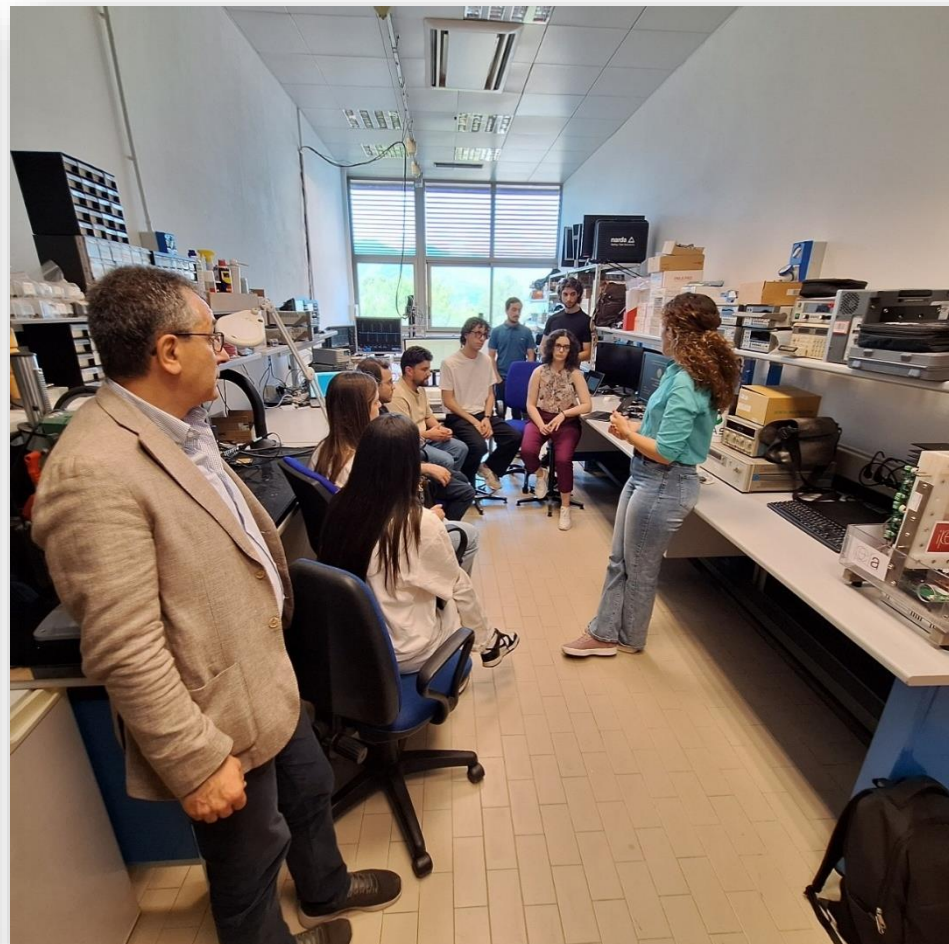
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# DEXTER: dissemination initiatives







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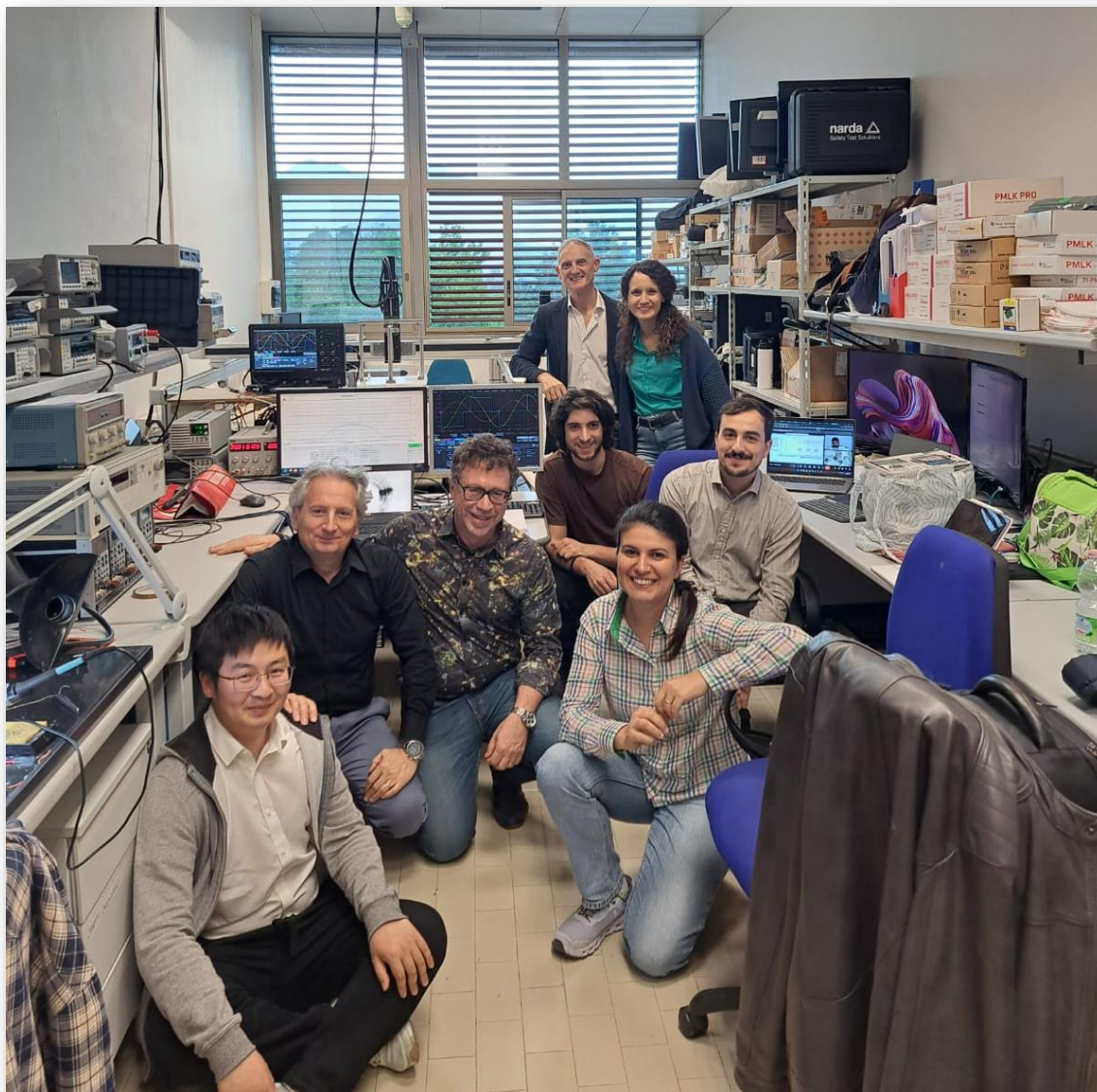


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## The DEXTER Team



UNICAS



Giulia Di Capua (PI)



Antonio Maffucci



Gennaro Di Mambro



UNISA



Nicola Femia



Luca De Guglielmo – partnership EXELING s.r.l.



Nunzio Oliva – partnership EXELING s.r.l.



UNIPI



Nunzia Fontana



Sami Barmada



Junda Zhu





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# Thank you for your attention

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